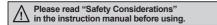
Features

• Minimized blind zone with 3-point cross-beam netting method

Long sensing distance: 1 to 7m

• 7 types of model

- : wide range of choice in the number of optical axis (4 to 20), pitch of optical axis (40, 80mm), and sensing width (120 to 1,040mm)
- Easy installation with installation mode
- Built-in interference protection, self-diagnosis function
- Self-diagnosis output
 - : sensing front screen contamination and covering optical axis by itself, making easy to see the status from external equipment (patent)
- Conspicuous high luminance indicators at emitter/receiver for easy check of the status from side, front even long distance
- Suitable for KRS Korean Railway Srandard (BWC80-14HD meets KRS conditions.)
- Protection structure IP67 (IEC structure)





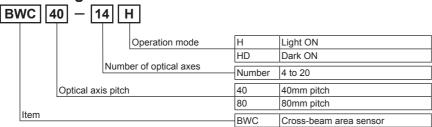
Applications

(only for BWC80-14HD model)

Various environment:

Utilized in various environment: obstacle detecting sensor for subway platform screen door (PSD), and etc.

Ordering Information



Specifications

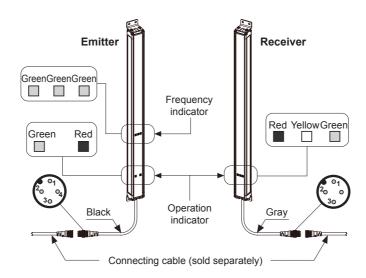
Model	BWC40-□□H	BWC40-□□HD	BWC80-14H	BWC80-14HD		
Sensing type	Through-beam type					
Sensing distance	1.0 to 7.0m					
Sensing target	Opaque material of min. Ø50mm		Opaque material of min. Ø	ð90mm		
Optical axis pitch	40mm		80mm			
Number of optical axes	4/10/12/16/18/20		14			
Sensing height	120 to 760mm		1,040mm			
Beam pattern	3-point cross-beam netting type					
Response time	Max. 50ms					
Power supply	12-24VDC== ±10% (ripple P-P: r	12-24VDC== ±10% (ripple P-P: max. 10%)				
Current consumption	Max. 100mA					
Light source	Infrared LED (850nm modulated)					
Operation mode	Light ON	Dark ON	Light ON	Dark ON		
Control output	NPN open collector output • Load voltage: max. 30VDC== • Load current: max. 100mA(self-diagnosis output: max 50mA) • Residual voltage: max. 1VDC==					
Protection circuit	Reverse power polarity, output sl	Reverse power polarity, output short over current protection circuit				
Insulation resistance	Over 20MΩ (at 500VDC megger)				
Synchronization type	Timing method by synchronous of	cable				
Self-diagnosis	Transmitted-received light monitoring, direct light monitoring, output circuit monitoring, self-diagnosis output (checking whether there is contamination on the front screen, or any obstacle on optical axis)					
Interference protection	Interference protection by frequency changing setting					
Noise immunity	±240V the square wave noise (p	ulse width: 1µs) by the nois	e simulation			
Dielectric strength	1,000VAC 50/60Hz for 1 min					
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours					

Shaded parts () are changed and added functions from previous BWC Series.



Model		BWC40- H BWC40- HD BWC80-14H BWC8				
Shock		500m/s2 (approx. 50G) in each X	X, Y, Z direction for 3 tir	mes		
	Ambient illumination	Ambient light: max. 100,000lx (re	Ambient light: max. 100,000lx (received light side illumination)			
Environ- ment	Ambient temperature	-10 to 55°C, storage: -20 to 60°C	-10 to 55°C, storage: -20 to 60°C			
	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH				
Protection	structure	IP65 (IEC standard)				
Material		Case: Aluminum, sensing part a	nd indicator: Acrylic			
Cable		Ø5mm, 4-wire, 300mm, M12 cor	nector			
Accessory	pry Bracket A: 4, Bracket B: 4, Fixing bolt: 8					
Korean Rail	lway Standards	KRS SG 0068				
Approval	at CE CE, IE				C€, เ≰	
Weight ^{X1} Approx. 2.1kg (approx. 1.7kg) (based on BWC80-14H)			•			

Structure



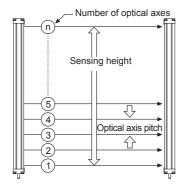
< Operation indicator>

LED color	Emitter	Receiver
Green	Power	Stable light ON
Yellow	_	Unstable area
Red	Installation mode	Stable light OFF
		-

<Wiring connection>

Pin No	Cable color	Emitter	Receiver
1	Brown	12-24VDC	12-24VDC
2	White	Sync	Sync
3	Blue	0V	0V
4	Black	Mode	OUT

■ Optical Axis Pitch/Number Of Optical Axes/Sensing Height



Model	Number of optica axes	Sensing height	Optical axis pitch
BWC40-04H/HD	4	120mm	
BWC40-10H/HD	10	360mm	
BWC40-12H/HD	12	440mm	40mm
BWC40-16H/HD	16	600mm	40111111
BWC40-18H/HD	18	680mm	
BWC40-20H/HD	20	760mm	
BWC80-14H/HD	14	1,040mm	80mm

MOTION DEVICES SOFTWARE

CONTROLLERS

SENSORS

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

Vision Sensors

(F) Proximity Sensors

Pressure Sensors

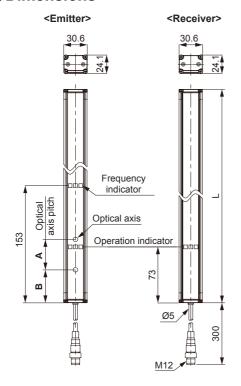
(H) Rotary Encoders

Connectors/ Connector Cables/ Sensor Distribution

Autonics

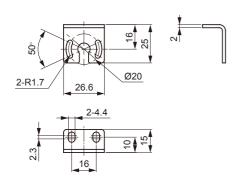
 $[\]times$ 1: The weight includes packaging. The weight in parenthesis is for unit only. \times The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Dimensions

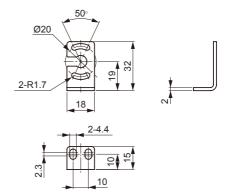


Model	L	A, B
BWC40-04H/HD	160	
BWC40-10H/HD	400	
BWC40-12H/HD	480	40
BWC40-16H/HD	640	40
BWC40-18H/HD	720	
BWC40-20H/HD	800	
BWC80-14H/HD	1120	80

Bracket A



Bracket B



■ Bracket Mounting

• Mounting the bracket A

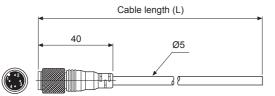


• Mounting the bracket B



C-24 Autonics

■ Connection Cable (sold separately)



**Connection cable is sold separately as one set; each of emitter's and receiver's.

Туре	Model	L	Cable color
For emitter	CID4-3T	3m	
	CID4-5T	5m	Black
	CID4-7T	7m	Black
	CID4-10T	10m	
	CID4-3R	3m	
For receiver	CID4-5R	5m	Grav
	CID4-7R	7m	Glay
	CID4-10R	10m	

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

Operation Mode

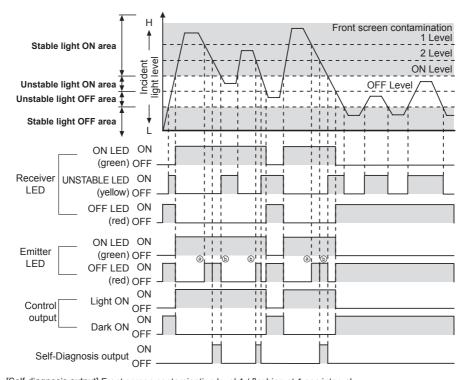
Operation mode	Light ON	Dark ON	
Receiver	Received light Interrupted light	Received light Interrupted light	
Operation indicator (Green LED)	ON OFF	ON OFF	
Transistor output	ON OFF	ON OFF	

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) LIDAR Sensors

Operation Timing Diagram



*(a): [Self-diagnosis output] Front screen contamination level 1 / flashing at 1 sec interval

(b): [Self-diagnosis output] Front screen contamination level 2, covering optical axis / flashing at 0.25 sec interval

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

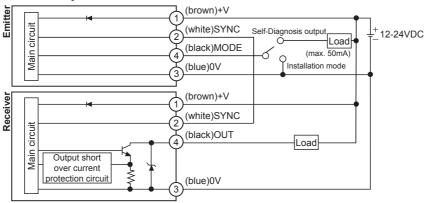
(G) Pressure Sensors

(H) Rotary Encoders

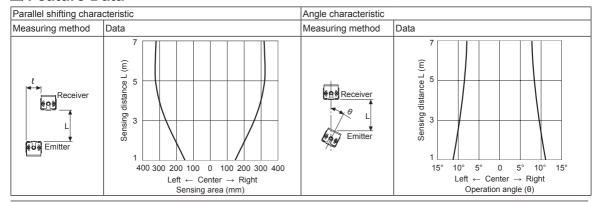
Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

Autonics C-25

Control Output Circuit



■ Feature Data



Functions

Interference protection

You can change transmitted light frequency to prevent interference from several units.

To change transmitted light frequency, input 0V for over 1 second to 4th terminal, (black) MODE, in installation mode.

Frequency type is displayed by frequency indicator.

Installation mode

This function is for stable installation.

Inputting 0V to 4th terminal of emitter which is (black) MODE, supply power to the product to enter to the installation mode.

Self-Diagnosis Output

This function outputs self-diagnosis signal, when front screen is contaminated with dust, optical axis is misaligned due to vibration, emitter is damaged due to the long-term usage, or light t is not received due to obstacle such as leaves and trash on the product. It operates in the operation mode, and you can check the status through an external device which is connected to 4th terminal of emitter, (black) MODE.

Item	Emitter operation indicator	Control ou	l output Self-diagno	
llein	Emilier operation indicator	Light ON Dark ON output		output
Front screen contamination level 1	Red, flashing at 1 sec interval	ON	OFF	OFF
Front screen contamination level 2, covering optical axis	Red, flashing at 0.25 sec interval	ON	OFF	ON

Self-diagnosis

If there is checked malfunction during normal operation by regular self-diagnosis, control output turns OFF and operation indicator displays the state.

Diagnosis item

- 1 Break of light emitting element
- 3 Break of adjacent emitting element more than 2.
- ⑤ Emitter failure
- Malfunction of synchronous cable

☼: ON, ●: OFF

Transmitted	Frequency indicator					
light frequency	Green 1	Green 2	Green 3			
Frequency A	≎	•	•			
Frequency B	•	≎	•			
Frequency C	•	•	≎			
Frequency D	≎	•	≎			
Frequency E	≎	≎	≎			

- ② Break of emitter
- 4 Break of receiver
- Receiver failure
- ※For more information about operation indication display, refer to "■ Operation Indicator"

C-26

Operation Indicator

				Receive	er			
Item		Indicator		Indicato	Indicator		Control output	
		Green	Red	Green	Yellow	Red	Light ON	Dark ON
Power supp	ply	≎	•	—	I—	<u> </u>	1—	_
Break of er	nitter	D	(4)	 		 —	—	_
Break of lig	ht emitting element	▶	•	((b)	(b)	OFF	OFF
Break of ac emitting ele	djacent ement more than 2.	•	•	•	(•	OFF	OFF
	Normal installation	≎	•	♦	•	•	OFF	OFF
Installation mode	Hysterisis section	•	•	•	≎	•		
illoue	Abnormal installation	•	•	•	•	•		
Stable light	ON	≎	•	\$	•	•	ON	OFF
Unstable lig	ght ON	≎	•	₽	≎	•	ON	OFF
Unstable lig	ght OFF	•	≎	•	≎	≎	OFF	ON
Stable light	: OFF	•	≎	•	•	≎	OFF	ON
Break of receiver			I—	D D	•	● ●	OFF	OFF
Control output over current		_		(•	≎	OFF	OFF
Synchronous line malfunction		_		•	•	•	OFF	OFF
Emitter fail	ure (time out)		1—	•	•	•	OFF	OFF
Receiver fa	ilure (time out)	0	0	1	1	1	OFF	OFF

Indicato	rs	
≎	Lighting	
•	Light out	
	Flashing	
	at 0.5 sec interval	
• or	Flashing simultaneously	
	at 0.5 sec interval	
0.0	Cross-flashing	
⋑◀	at 0.5 sec interval	
000	Sequence-flashing	
	at 0.5 sec interval	

CONTROLLERS MOTION DEVICES

SOFTWARE

SENSORS

(B) Fiber Optic Sensors

(A) Photoelectric Sensors

(C) LIDAR Sensors

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

■ Troubleshooting

Malfunction	Cause	Troubleshooting
Non-operation	Power supply	Supply the rated power.
	Cable incorrect connection, or isconnection	Check the wiring connection
	Out of rated sensing distance	Use it within rated sensing distance.
Non-operation in sometimes Control output is OFF even though there is not a target object.	Pollution by dirt of sensor cover	Remove dirt by soft brush or cloth.
	Connector connection failure	Check the assembled part of the connector
	Out of the rated sensing distance	Use it within the rated sensing distance.
	There is an obstacle to cut off the emitted light between emitter and receiver.	Remove the obstacle.
	There is strong electric wave or noise generator such as motor, electric generator, or high voltage line, etc.	Put away the strong electric wave or noise generator.
Operation indicator displays break of emitter	Break of emitter	Contact our company.
Operation indicator displays break of receiver	Break of receiver	
Operation indicator displays break of light emitting element	Break of light emitting element	
Operation indicator displays emitter/receiver failure	Emitter or Receiver failure	
	Bad wiring connection of synchronous cable in emitter and receiver	Check the wiring connection in emitter and receiver.
Check the wiring connection in	Control output line is shorted out.	Check the wiring connection.
emitter and receiver.	Over load	Check the rated load capacity.

Autonics C-27

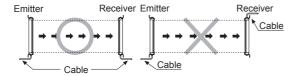
Installation

For the first installation, enter installation mode.

- Entry method for installation mode: Supply the power with inputting 0V to terminal 4 (black) MODE of Emitter.
- ② After entering installation mode, install the unit at the position where green LED of receiver operation indicator turns ON
- 3 After installation, re-supply the power to the unit.

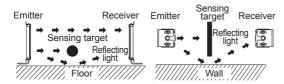
For direction of installation

Emitter Receiver should be installed in same up/down direction.



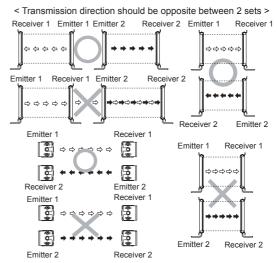
For reflection from the surface of wall/flat

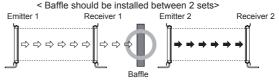
When installing it as below, the light reflected from the surface of wall and flat is not shaded. Please check whether it operates normally or not with a sensing target before using. (interval distance: min. 0.5m)



For protection of interference

It may cause interference when installing more than 2 sets of the sensor. In order to avoid the interference of the sensor, please install as following figures and use interference protection function





<It should be installed out of the interference distance>



- XIt may be different by installation environment.
- «Avoid using the unit in the place where the sensor is exposed directly to the fluorescent light with high speed start or high frequency.

Proper Usage

- 1. Follow instructions in 'Cautions during Use'.
 - Otherwise, It may cause unexpected accidents.
- 2. 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. Use the product, 1 sec after supplying power.
 - When using separate power supply for the sensor and load, supply power to sensor first.
- 4. When using switching mode power supply to supply the power, ground F.G. terminal and connect a condenser between 0V and F.G. terminal to remove noise.
- 5. When connecting a DC relay or other inductive load, remove surge by using diodes or varistors.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise.
- 7. This unit may be used in the following environments.
 - ①Indoors (in the environment condition rated in 'Specifications')
 - ②Altitude max. 2,000m
 - 3 Pollution degree 2
 - ④Installation category II