

Shaft Type Ø15mm Incremental Rotary Encoder

■ Features

- Ultra-compact (Ø15mm) and ultra-lightweight (14g)
- Easy installation in tight or limited spaces
- Low moment of inertia
- Power supply: 5VDC ±5%



⚠ Please read "Safety Considerations" in the instruction manual before using.

■ Ordering Information

Item		Shaft Type Ø15mm Incremental Rotary Encoder	
Model		E15S2-36-2-N-5-R	
Resolution (PPR) ^{※1}		36	
Electrical specification	Output phase	A, B phase	
	Phase difference of output	Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)	
	Control output	NPN open collector output - Load current: max. 30mA, Residual voltage: max. 0.4VDC=	
	Response time (rise/fall)	Max. 1μs (cable length: 1m, I sink=20mA)	
	Max. response frequency	10kHz	
	Power supply	5VDC= ±5% (ripple P-P: max. 5%)	
	Current consumption	Max. 50mA (disconnection of the load)	
	Insulation resistance	Over 100MΩ (at 500VDC megger between all terminals and case)	
	Dielectric strength	500VAC 50/60Hz for 1 min (between all terminals and case)	
	Connection	Axial cable type	
Mechanical specification	Starting torque	Max. 10gf·cm (9.8×10 ⁻⁴ N·m)	
	Moment of inertia	Max. 0.5g·cm ² (5×10 ⁻⁸ kg·m ²)	
	Shaft loading	Radial: 200gf, Thrust: 200gf	
	Max. allowable revolution ^{※2}	3,000rpm	
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours	
Shock		Approx. max. 50G	
Environment	Ambient temperature	-10 to 70°C, storage: -20 to 80°C	
	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH	
Protection structure		IP50 (IEC standard)	
Cable		Ø3mm, 4-wire, 500mm, Flexible PVC insulation shielded cable (AWG30, core diameter: 0.102mm, number of cores: 7, insulator diameter: Ø0.71mm)	
Accessory		Ø2mm coupling	
Weight ^{※3}		Approx. 37g (approx. 14g)	

※1: Not indicated resolutions are customizable.

※2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

$$[\text{Max. response revolution (rpm)}] = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$$

※3: The weight includes packaging. The weight in parenthesis is for unit only.

※Environment resistance is rated at no freezing or condensation.

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

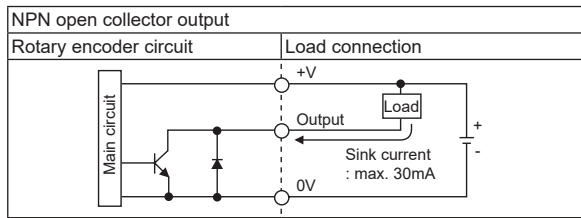
(G) Pressure Sensors

(H) Rotary Encoders

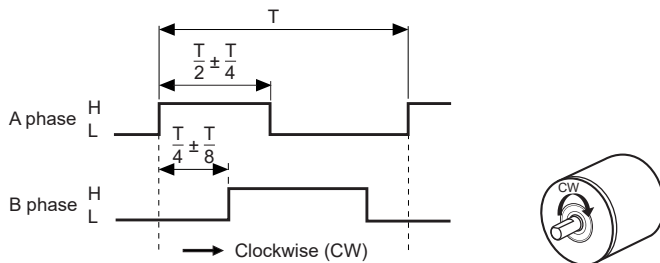
(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

E15S2-36-2-N-5-R

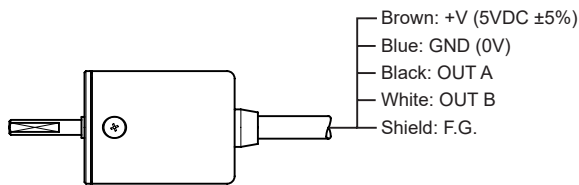
Control Output Diagram



Output Waveform



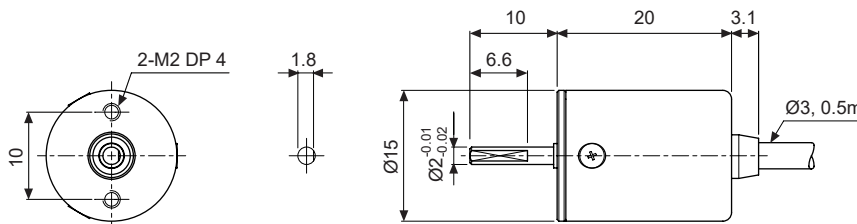
Connections



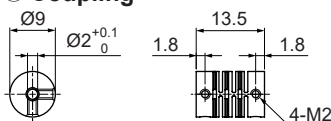
- ※Unused wires must be insulated.
- ※The metal case and shield cable should be grounded (F.G.).
- ※Do not apply tensile strength over 15N to the cable.

Dimensions

(unit: mm)



Coupling



- Parallel misalignment: max. 0.15mm
- Angular misalignment: max. 2°
- End-play: max. 0.5mm

- ※Do not load overweight on the shaft.
- ※Do not put strong impact when insert a coupling into shaft.
Failure to follow this instruction may result in product damage.
- ※Fix the unit or a coupling by a wrench under 0.15N·m of torque.
- ※When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.
- ※For parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description.
- ※For flexible coupling (ERB series) information, refer to the ERB series section.